

Divergence Thm / Stoke's Thm.

Recall Green's Thm

$$(*) \oint_{\partial D} \vec{F} \cdot \vec{T} \cdot ds = \iint_D (Q_x - P_y) dx dy$$

(work)

∂D : simple closed
counter clock wise

$$(**) \oint_{\partial D} \vec{F} \cdot \vec{N} \cdot ds = \iint_D (P_x + Q_y) dx dy$$

(flux)



To generalize (**) we replace $\oint_{\partial D}$ with \oiint_S

Divergence Thm:

$$\oiint_S \vec{F} \cdot \vec{N} \cdot ds = \iiint_T \underbrace{\vec{\nabla} \cdot \vec{F}}_{P_x + Q_y + R_z} dx dy dz$$

S : closed surface

\vec{N} : outward normal

eg. S : unit sphere.

$\vec{F} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$ what is the flux with outward normal?

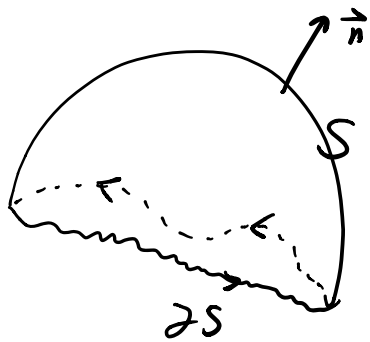
$$\oiint_S \vec{F} \cdot \vec{N} \cdot ds = \iiint_{\text{mit ball}} 3 \cdot dx dy dz = 3 \cdot \text{Vol}(\text{mit ball})$$

$$= 3 \cdot \frac{4}{3} \pi = 4\pi$$

$\vec{F} = \begin{pmatrix} y \\ z \\ x \end{pmatrix}$ what is the flux? 0.

because $\vec{\nabla} \cdot \vec{F} = 0$

To generalize (*) :



Stoke's Thm:

$$\oint_{\partial S} \vec{F} \cdot \vec{T} ds = \iint_S (\text{curl } \vec{F}) \cdot \vec{N} \cdot dA$$

$$\oint_{\partial S} \vec{F} \cdot d\vec{r}$$

Orientation: use right hand to determine orientation

Thumb \vec{N} for S

4 Fingers \vec{T} for \vec{r}

$$\oint_{\partial D} \vec{F} \cdot \vec{T} \cdot ds = \iint_D (Q_x - P_y) dx dy$$

(work)

$$\vec{F}' = \begin{pmatrix} P \\ Q \\ 0 \end{pmatrix} \quad \text{curl } \vec{F}' = \begin{vmatrix} i & j & k \\ \partial_x & \partial_y & \partial_z \\ P & Q & 0 \end{vmatrix}$$

$$= \begin{pmatrix} 0 \\ 0 \\ Q_x - P_y \end{pmatrix}$$

$$\text{curl } \vec{F}' \cdot \vec{N} = Q_x - P_y$$