

Week 15 Tuesday.

Recall that.

$$A \in M_{n \times n}(\mathbb{R})$$

In order to diagonalize  $A$ , we solve

1)  $\det(A - \lambda I) = 0 \rightarrow \text{eigenvalue}$

2) For each eigenvalue  $\lambda$ , solve  $(A - \lambda I) \cdot \vec{x} = 0$ .

$\rightarrow$  eigenvector(s)  $V_\lambda := \{\vec{v} \mid A\vec{v} = \lambda v\}$ .

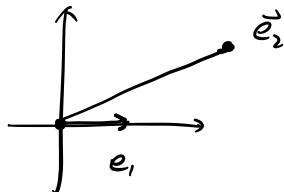
If  $\sum_{\lambda} \dim(V_\lambda) = n$ , then we can find a basis  
 $S = \{\vec{v}_1, \dots, \vec{v}_n\}$

of  $\mathbb{R}^n$  that are all eigenvectors.  $\Rightarrow P^{-1}AP = D$

$$P = \begin{pmatrix} v_1 & \dots & v_n \\ \downarrow & \dots & \downarrow \end{pmatrix}$$

Not always diagonalizable:

e.g.  $A = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix} \quad \mathbb{R}^2$



For symmetric matrix, such bad situation never happens.

Theorem.  $A \in M_{n \times n}(\mathbb{R})$   $A = A^\top$ , then  $A$  can always be diagonalized.

Rmk. Recall. Last time: if  $\lambda_1 \neq \lambda_2$  are different eigenvalues, then  $V_{\lambda_1}$  and  $V_{\lambda_2}$  are orthogonal to each other.

So, if  $A$  can be diagonalized, then  $A$  can also be orthogonally diagonalized.

$\cdots \cdot \cdots \cdots \partial$

Prop.: Block Matrix.

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} a' & b' \\ c' & d' \end{pmatrix} = \begin{pmatrix} a \cdot a' + bc & a \cdot b' + b \cdot d' \\ c \cdot a' + d \cdot c' & c \cdot b' + d \cdot d' \end{pmatrix}$$

$$\left( \begin{array}{c|c} A & B \\ \hline C & D \end{array} \right) \left( \begin{array}{c|c} A' & B' \\ \hline C' & D' \end{array} \right) = \begin{pmatrix} A \cdot A' + B \cdot C' & A \cdot B' + B \cdot D' \\ C \cdot A' + D \cdot C' & C \cdot B' + D \cdot D' \end{pmatrix}$$

Pf. Firstly, we can always find at least one eigenvalue  $\lambda_1$  for  $A$ . then. solve  $(A\lambda_1 - I)\vec{x} = 0$ . so we can find at least one eigenvector  $\vec{v}_1$  for  $A$ .

Assume  $\vec{v}_1$  is normalized, and extend it to an orthonormal basis.  $\{\vec{v}_1, \dots, \vec{v}_n\}$ . take  $P = (\downarrow \downarrow \downarrow)$   
(use Gram-Schmidt)

$$P^T A P = \begin{pmatrix} \lambda_1 & & \\ 0 & & \\ 0 & & \\ 0 & & A_2 \end{pmatrix} \rightarrow \begin{pmatrix} \lambda_1 & 0 \\ 0 & A_2 \end{pmatrix}$$

Since  $A$  is symmetric,  $P$  is orthogonal matrix. ( $P \cdot P^T = I$ )

$(P^T A P)^T = P^T A^T (P^{-1})^T = P^T A P$  is symmetric

$$\Rightarrow A_1 = \underbrace{1 \ 0 \ 0 \ 0}_{\text{...}} \quad A_2 = A_2^T.$$

Use induction: ① For  $n=1$ .  $A$  is scalar. always true.

② Assume for  $k < n$   $A \in M_{k \times k}(R)$  is always diagonalizable

Now. by ②. we can pick  $Q \in M_{n-1 \times (n-1)}$  orthonormal. s.t.

$$Q^T \cdot A_2 \cdot Q = D \text{ is diag}$$

Therefore.  $\tilde{Q} := \begin{pmatrix} 1 & 0 \\ 0 & Q \end{pmatrix}$        $\tilde{Q}^{-1} := \begin{pmatrix} 1 & 0 \\ 0 & Q^{-1} \end{pmatrix}$

we can get

$$\begin{aligned} & \tilde{Q}^{-1} \cdot \begin{pmatrix} 1 & 0 \\ 0 & A_2 \end{pmatrix} \cdot \tilde{Q} \\ &= \begin{pmatrix} 1 & 0 \\ 0 & Q^{-1} \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & A_2 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 \\ 0 & Q \end{pmatrix} \\ &= \begin{pmatrix} 1 & 0 \\ 0 & Q^{-1} A_2 Q \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & \begin{matrix} d_1 & & & \\ & \ddots & & \\ & & \ddots & \\ & & & d_{n-1} \end{matrix} \end{pmatrix} \end{aligned}$$

□.

## 2. Quadratic Form.

$$f(x, y) = x^2 + 2xy - 3y^2 \quad \xrightarrow{y^2} \quad \begin{array}{l} \tilde{x} = \frac{x+y}{\sqrt{2}} \\ \tilde{x}^2 + 2\tilde{x} - 3 \end{array}$$

$$\begin{array}{ll} \text{Graph: } \begin{array}{c} \text{A 2D coordinate system showing a hyperbolic paraboloid surface opening upwards along the x-axis. The surface is symmetric about the x-axis. The axes are labeled x and y. The origin is marked with O. The surface is labeled with } \frac{1}{4}(x+y)^2 \text{ above the positive x-axis and } \frac{1}{4}(x-y)^2 \text{ below the negative x-axis. The surface is bounded by the lines } x+y=0 \text{ and } x-y=0. \end{array} & x^2 + 2xy - 3y^2 \\ & = \underbrace{x^2 + 2xy}_{} + y^2 - y^2 - 3y^2 \\ & = (x+y)^2 - 4y^2 \\ & = [(x+y) + 2y][(x+y) - 2y] \end{array}$$

$$= (\tilde{x} + \alpha)^2 + \beta$$

$$\begin{aligned} & \tilde{x}^2 + 2\tilde{x} + 1 - 1 - 3 \\ &= (\tilde{x} + 1)^2 - 4 \end{aligned}$$

$$g(x, y) = xy = g_1(x, y) \pm g_2(x, y)$$

$$(x+1)^2 - 4$$

$$\frac{1}{4}(x+y)^2 - \frac{1}{4}(x-y)^2$$

$$ax^2 + bxy + cy^2 = ? g_1(x, y)^2 \pm ? g_2(x, y)^2$$

$$\begin{aligned}
 f(x, y) = ax^2 + 2bx + cy^2 &\xrightarrow{\text{??}} (x \ y) \begin{pmatrix} a & b \\ b & c \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \vec{x}^T \cdot A \cdot \vec{x} \\
 &= (ax + by \quad bx + cy) \cdot \begin{pmatrix} x \\ y \end{pmatrix} \\
 &= ax^2 + bxy + bxy + cy^2
 \end{aligned}$$

We see a bijection between.

homogeneous quadratic polynomials  $\longleftrightarrow$  symmetric matrices

complete the square  $\longleftrightarrow$   $A$  is diagonal

In general if  $P^T A P = D$  then  $A = P D P^{-1}$

$$\text{thus } \vec{x}^T \cdot A \cdot \vec{x} = \underline{\vec{x}^T \cdot P \cdot D \cdot P^{-1} \cdot \vec{x}}$$

then  $\vec{y} = P^{-1} \cdot \vec{x}$  linear transformation of  $\begin{pmatrix} x \\ y \end{pmatrix}$

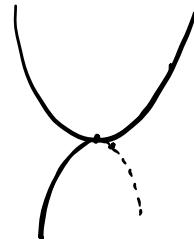
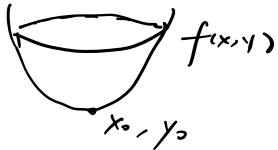
$$= \begin{pmatrix} P_1x + P_2y \\ P_3x + P_4y \end{pmatrix}$$

Recall calculus

$$\begin{aligned}
 f(x, y) = f(x_0, y_0) + \frac{\partial f}{\partial x}(x_0, y_0) \cdot (x - x_0) + \frac{\partial f}{\partial y}(x_0, y_0) \cdot (y - y_0) \\
 + \left[ \frac{\partial^2 f}{\partial x^2}(x_0, y_0) \cdot \frac{(x - x_0)^2}{2} + \frac{\partial^2 f}{\partial y^2}(x_0, y_0) \cdot \frac{(y - y_0)^2}{2} \right. \\
 \left. + \frac{\partial^2 f}{\partial x \partial y}(x_0, y_0) \cdot \frac{(x - x_0)(y - y_0)}{2} \right] + \dots
 \end{aligned}$$

$$f(x) = f(x_0) + \frac{af}{dx}(x_0) \cdot (x - x_0) + \frac{\frac{d^2f}{dx^2}(x_0)}{2} \cdot \frac{(x - x_0)^2}{2} + \dots$$

$f''(x_0) < 0$



local

min  
positive def

local max

negative def

saddle

indefinite

Def:  $Q(x, y) = ax^2 + 2bxy + cy^2$  then.

if  $Q(x, y) > 0$  for every  $(x, y) \neq (0, 0)$   $\Rightarrow$  positive definite

$Q(x, y) < 0$   $\Rightarrow$  negative definite

$Q(x, y)$  can be both positive and negative  $\Rightarrow$  indefinite